

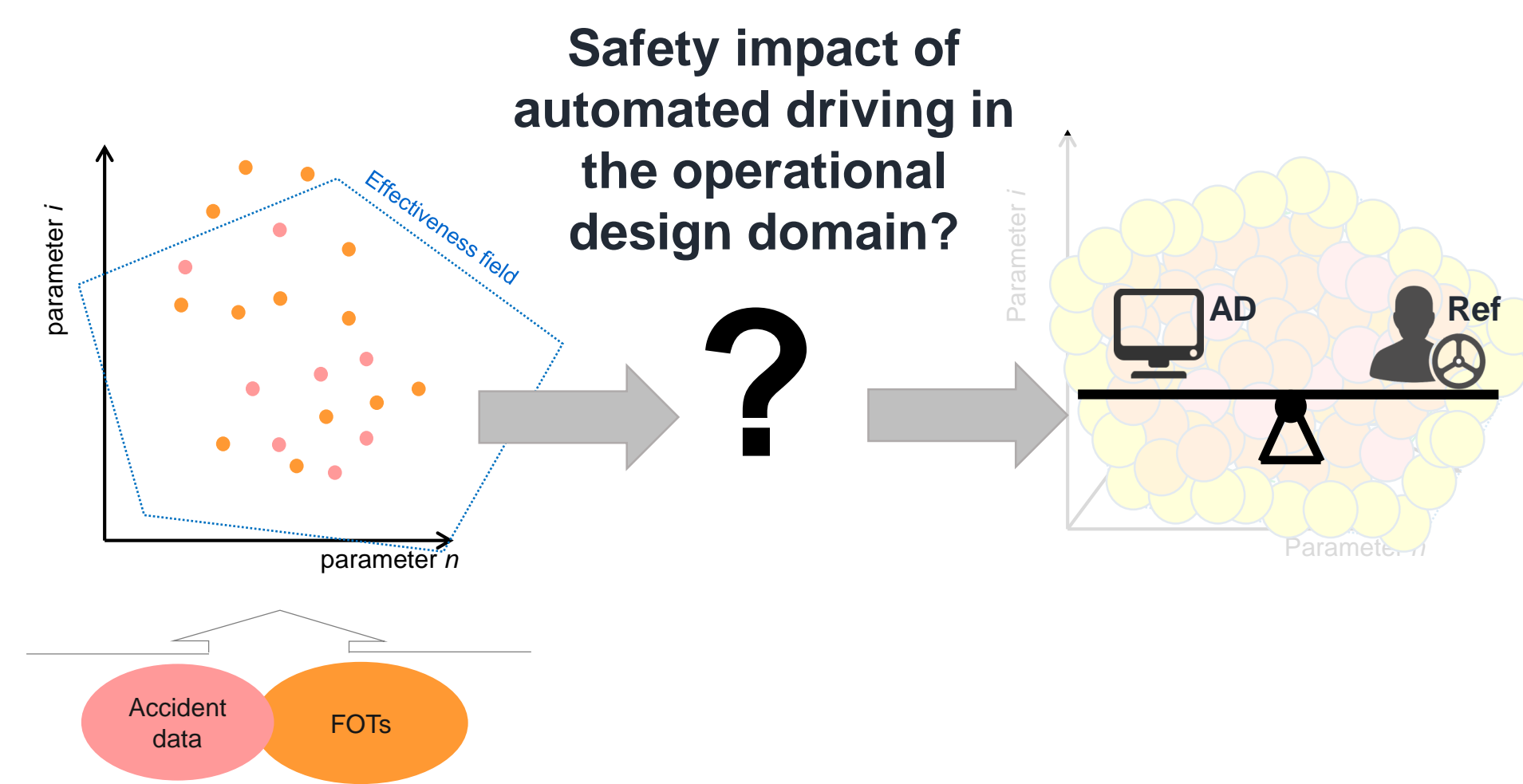
A Traffic-based Method for Safety Impact Assessment of Road Vehicle Automation

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Challenges

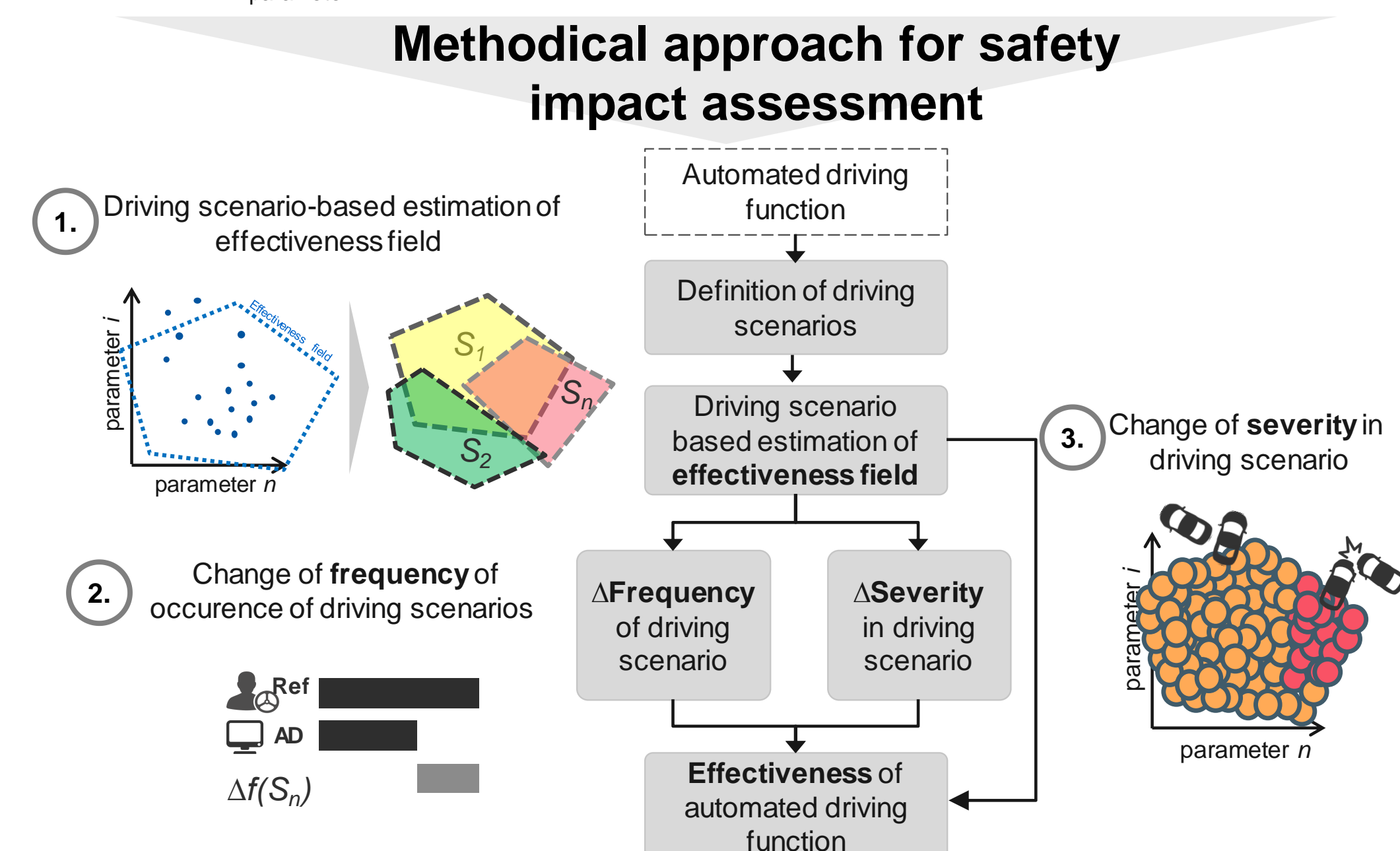
- One of the major challenges for enabling market introduction of automated driving is to **identify risks and benefits** of these functions.
- According to the *German Ethics Commission on Connected and Automated Driving* [1],
“[...] the licensing of automated systems is not justifiable unless it promises to produce at least a diminution in harm compared with human driving, in other words a positive balance of risks [...]”
- In order to assess this balance of risks, a method for safety impact assessment of continuously operating [2] automated driving functions with respect to human driver performance is necessary.



- Based on different data sources, such as national accident statistics [3], in-depth accident data [4] and FOT-data [5], a **simulation-based** approach for **prospective effectiveness assessment** has been realized.

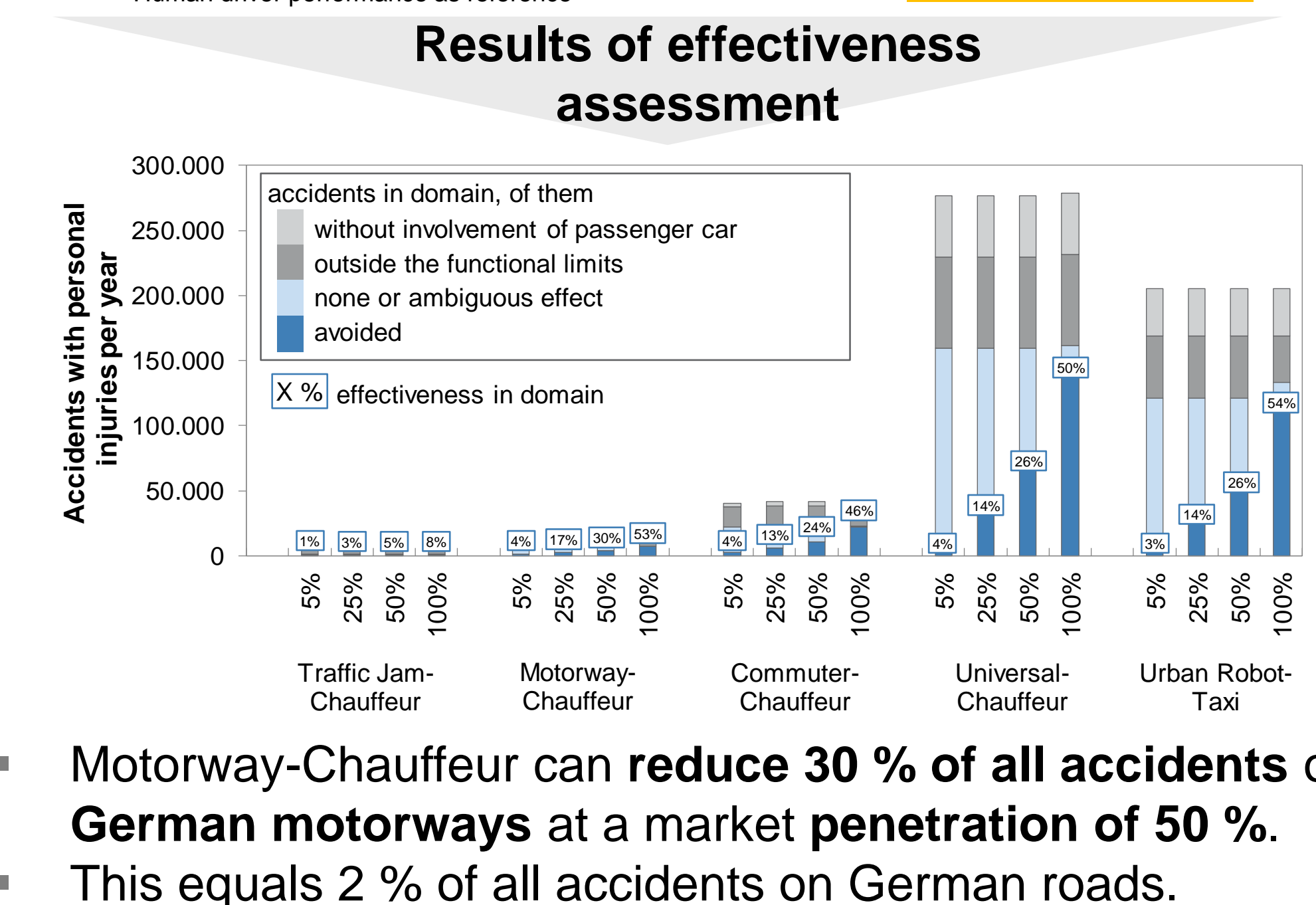
Method

- Driving scenario based estimation of effectiveness field**
 - Accidents addressed by automated driving functions form the **effectiveness fields** gained from **national accident statistics** and **in-depth accident data**.
- Δ Frequencies of driving scenarios**
 - Automated vehicles may not get involved in certain accident scenarios any longer while other, new accidents, will arise. **Changes in frequencies of driving scenarios** have to be assessed.
- Δ Severity in driving scenarios**
 - In incident situations, the **performance** of automated vehicles **is compared** to human driver performance for obtaining **Δ severity**.



Results

- Exemplary estimation of effectiveness fields of SAE level 3 “Motorway-Chauffeur”**
 - Accidents in Germany in 2016 (308,145 AP): Rural road 25%, County road 14%, Municipal road 38%, Federal highway 17%, Federal motorway 6%.
 - Accidents in domain „Motorway“ (19,010 AP): not addressable driving scenarios 12%, driver and vehicle related limits 9%, functional limits 14%, no car participation 2%.
 - Driving scenarios in effectiveness field (9,395 AP): Approaching static values 2%, Approaching leading vehicle 43%, Lane change 4%, Approaching traffic jam 18%, Unintended driving 7%, Passive cut-in 16%.
 - Number of accidents for scaling-up of effectiveness: Driving scenarios 1,219, Accidents 1,219.
 - Situational variables for effect of function by simulation: $v_{ref}=67$ km/h, $v_{ad}=93$ km/h.
- Traffic simulations** for identification of relevant driving scenarios [6]
 - Rear-end incidents: Comparison of traffic simulation data and FOT data showing a decrease in frequency of rear-end incidents as penetration rate of automated driving increases.
- Human driver performance models as reference for re-simulation**
 - Simulation of reference vs Simulation with ADF (Automated Driving Function) showing a **Reduction of severity (MAIS2+) by 42,3 %**.



- Motorway-Chauffeur can **reduce 30 % of all accidents on German motorways** at a market penetration of **50 %**.
- This equals **2 % of all accidents on German roads**.

Conclusion

- The **operational design domain** (e.g. environmental conditions) highly affects the **effectiveness** of an automated driving function.
- Changes in frequencies** (and thus relevance) of driving/accident scenarios have to be taken into account for safety assessment of AD.
- Human driver performance** has to be modelled as a reference for assessment.

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