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Background

- Nearly 7,000 pedestrian and bicyclist fatalities in 2016 (18 percent of total traffic fatalities).
- Conditions known to increase risk of incidents:
 - Crowded urban settings (occlusion by vehicles/objects).
 - Low visibility (inclement weather, dusk/dawn, nighttime).
- Vehicle-to-Pedestrian (V2P) technologies use external sensors to detect at-risk pedestrians.
- System may alert the driver or intervene to reduce risk or severity of a crash.
- Sensors used include:
 - Visual cameras/computer vision.
 - Light detection and ranging (LIDAR) sensors.
 - Millimeter wave radar.
 - Direct wireless communications.
- Capability assessment of diverse and emerging V2P technologies is ongoing.

Project Goals

Establish a testbed for emerging V2P technologies at **Turner-Fairbank Highway Research Center (TFHRC)**

Phase I: Develop a test plan strategy and identify V2P systems currently available on the consumer market

Technology Scan

- Identified 86 known V2P technologies. (https://www.its.dot.gov/press/2015/v2p_tech.htm)
- Very few mature, market-ready, and publicly accessible products.

Eligibility Criteria for testing at TFHRC:

- Perform in at least one of four test case scenarios.
- Deliver some measurable communication output delivered to driver/vehicle or pedestrian/bicyclist.
- Function within the environment provided (TFHRC or offsite).

Assessment Plan developed from common V2P features to assess technology accuracy, reliability, safety features, and market readiness, and accessibility

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Towards Establishing a Testbed for Vehicle-to-Pedestrian (V2P) Technology



Phase II: Assess safety effectiveness of market-ready V2P systems validating the test plan strategy from phase I

Assessment Plan

• Identified four scenarios common to vehicle-pedestrian collisions.

Left Turn

Straight

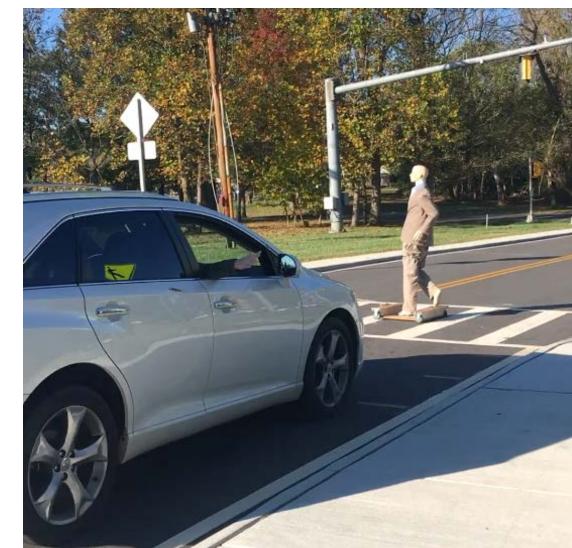
Figure 1. Four test cases

Assessment Plan Validation

- Acquired camera-based after-market safety device with pedestrian detection feature.
- Computer vision algorithms detect human form; analyze movement, direction, and distance to identify crash risk.

System characteristics:

- Communicates to driver only.
- Visual alert displayed when pedestrian is detected.
- of crash detected.
- Driver's responsibility to intervene in response to alert.





and bicyclist (right).

Right Turn Parallel = Pedestrian/bicyclist

Source: FHWA

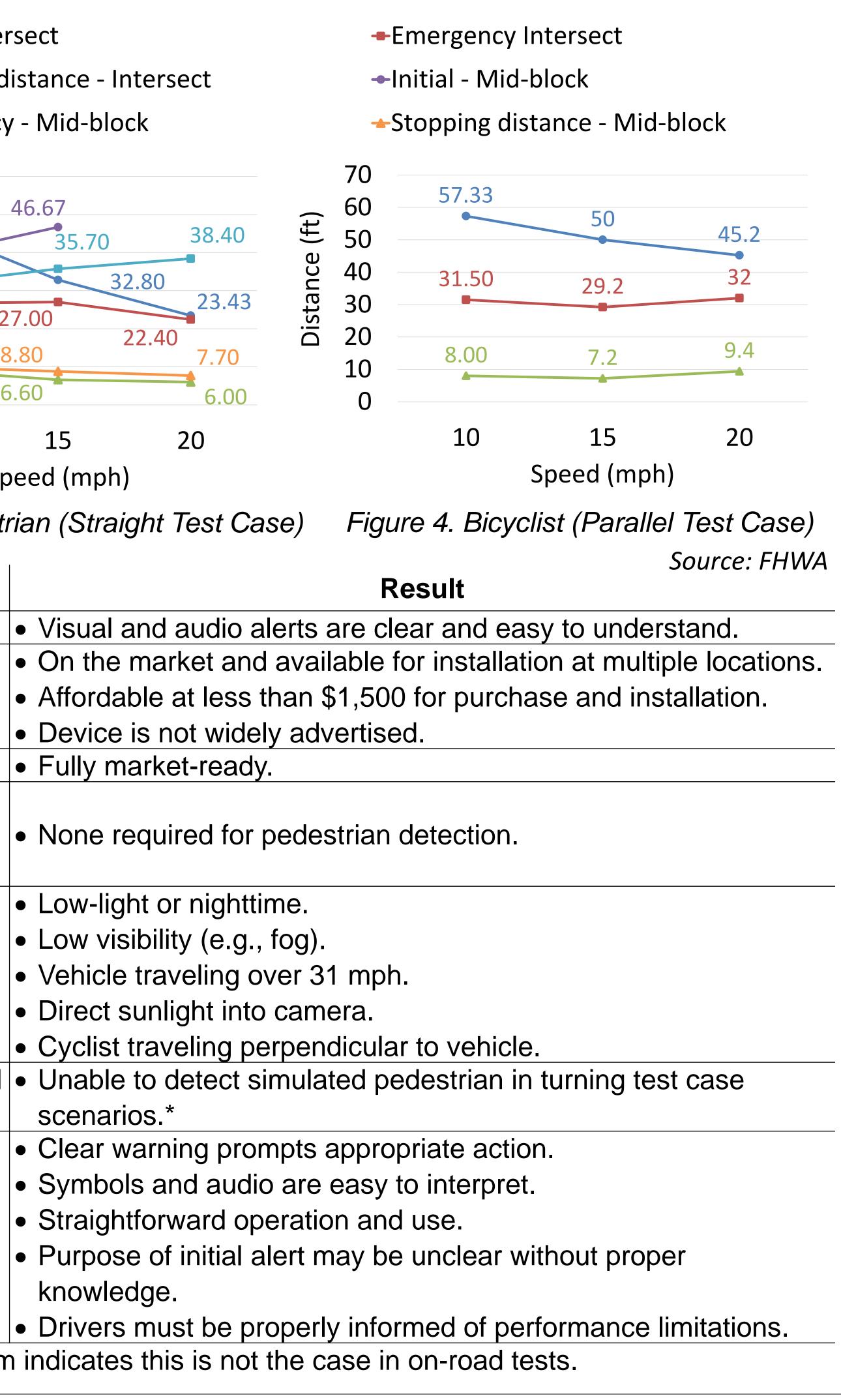
• Visual alert color change and audible alert when high risk

Figure 2a and 2b. Testing the validation system with simulated walking pedestrian (left)

Results **Alert and Response Distances** Initial Intersect Stopping distance - Intersect -Emergency - Mid-block 60 E7 22 47.00 (ft) 50 39.00 Ce 40 31.50 31.60 30 Dis 27.00 26.67 20 Ū 22.40 10 Speed (mph) Figure 3. Pedestrian (Straight Test Case) Measure Result Alert clarity User access to technology • Device is not widely advertised. • Fully market-ready. Readiness Institutional and None required for pedestrian detection. infrastructure requirements • Low-light or nighttime. • Low visibility (e.g., fog). Known nonfunctional Vehicle traveling over 31 mph. situations • Direct sunlight into camera. • Cyclist traveling perpendicular to vehicle. Additional discovered nonfunctionality scenarios.* Clear warning prompts appropriate action. Symbols and audio are easy to interpret. • Straightforward operation and use. Human factors assessment knowledge. *Note: Developer team indicates this is not the case in on-road tests. Conclusion • General testing plan validated with camera-based system. Simulated pedestrian characteristics limit some test cases. • System did not perform in turning test cases. • Specific technologies require tailored test approach.

Next steps: Acquire 3–5 additional V2P technologies, assess features, and test with customized plan.





Source: FHWA